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Motivation

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Motivation: Floer's proof of an Arnold-type Conjecture:

Theorem (Floer)

Let (M,ω) be a closed symplectic manifold, L a compact Lagrangian submanifold of M, and ψ a Hamiltonian diffeomorphism of (M,ω) . Assume that the symplectic area of any topological disc in M with boundary in L vanishes. Assume moreover that $\psi(L)$ and L intersect transversely. Then the number of intersection points of L and $\psi(L)$ satisfies the lower bound

$$#(\psi(L) \cap L) \ge \sum_{i} \dim H^{i}(L; \mathbb{Z}/2).$$

Floer's Approach

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Idea: Given a tranversely intersecting pair of Lagrangian submanifolds L_0, L_1 , construct a chain complex $CF(L_0, L_1)$ freely generated by the intersection points $\in L_0 \cap L_1$, satisfying:

• $\partial^2 = 0$, so that the (Lagrangian) Floer (co)homology

$$HF(L_0, L_1) := \ker \partial / \operatorname{im} \partial$$

is well-defined

• if L_1 and L'_1 are Hamiltonian isotopic, then

$$HF(L_0, L_1) \simeq HF(L_0, L_1')$$

• if L_1 is Hamiltonian isotopic to L_0 , then (with suitable coefficients)

$$HF(L_0, L_1) \simeq H^*(L_0)$$

Smooth Trajectories Between Two Lagrangians

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Applications

Let L_0, L_1 be compact Lagrangian submanifolds of symplectic manifold (M, ω) that intersect transversely (and hence at finitely many points).

• The space of smooth trajectories from L_0 to L_1 , endowed with the C^{∞} -topology:

 $\mathcal{P}(L_0, L_1) := \{ \gamma : [0, 1] \to M \mid \gamma \text{ smooth, } \gamma(0) \in L_0, \gamma(1) \in L_1 \}$

- constant paths $\in \mathcal{P}(L_0, L_1) \longleftrightarrow$ intersection points $\in L_0 \cap L_1$
- For a fixed γ̂ ∈ P(L₀, L₁), let P(γ̂) denote the connected component of P(L₀, L₁) containing γ̂.

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• The universal cover of $\mathcal{P}(\hat{\gamma})$ is

 $\widetilde{\mathcal{P}}(\widehat{\gamma}) = \{(\gamma, [\Gamma]) : \gamma \in \mathcal{P}(\widehat{\gamma}), \Gamma : \text{smooth homotopy from } \widehat{\gamma} \text{ to } \gamma\}$

(i.e. $\Gamma : [0,1] \times [0,1] \to M$ smooth with $\Gamma(s, \cdot) \in \mathcal{P}(\hat{\gamma})$ for all $s \in [0,1]$, $\Gamma(0, \cdot) = \hat{\gamma}$, and $\Gamma(1, \cdot) = \gamma$.)

• The action functional ${\mathcal A}$ is defined on $\widetilde{{\mathcal P}(\hat{\gamma})}$ by

$$\begin{aligned} \mathcal{A}(\gamma, [\Gamma]) &:= & -\int_{\Gamma} \omega \\ &= & -\int_{[0,1]\times[0,1]} \Gamma^* \omega \\ &= & -\int_0^1 \int_0^1 \omega \left(\frac{\partial\Gamma}{\partial s}, \frac{\partial\Gamma}{\partial t}\right) \mathrm{d}s \wedge \mathrm{d}t \end{aligned}$$

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WARNING: Actually, I lied: A is not well-defined!

We impose the following assumption (which will also avoid other complications later):

Assume that for each i = 0, 1,

 $[\omega] \cdot \pi_2(M, L_i) = 0,$

i.e. any topological disk in ${\cal M}$ with boundary in L_i has vanishing symplectic area.

Note that, in particular, this implies that M is symplectically aspherical, i.e.

$$[\omega] \cdot \pi_2(M) = 0.$$

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To see that \mathcal{A} is well-defined: Let $\gamma \in \widetilde{\mathcal{P}(\hat{\gamma})}$ and Γ , Γ' be homotopic smooth homotopies from $\hat{\gamma}$ to γ .

- We have the cylinder $\overline{\Gamma} \# \Gamma' : S^1 \times [0,1] \to M$, where $\overline{\Gamma} \# \Gamma'(s,i)$ is a loop in L_i , for i = 0, 1.
- Γ, Γ' are homotopic $\Rightarrow \Gamma(s, i), \Gamma'(s, i)$ are homotopic in $L_i \Rightarrow$ there exist topological disks whose boundaries are $\overline{\Gamma} \# \Gamma'(s, i) \subset L_i$
- L_i Lagrangian \Rightarrow these disks have symplectic area 0
- symplectic asphericity \Rightarrow symplectic area of the cylinder is also 0:

$$0 = \int_{\overline{\Gamma} \# \Gamma'} \omega = \int_{\Gamma} \omega - \int_{\Gamma'} \omega$$

Riemannian Metric

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Applications

To do Morse theory, we need a gradient flow, and hence we need a Riemannian metric on $\widetilde{\mathcal{P}(\hat{\gamma})}$.

<u>Recall</u>: Let $J \in End(TM)$ be an almost complex structure on (M, ω) .

• J is ω -compatible if

$$\omega(v, Jv) > 0, \quad \forall v \in T_x M, \forall x \in M,$$

and

$$\omega(J\cdot, J\cdot) = \omega(\cdot, \cdot).$$

• If J is ω -compatible, then it induces a Riemannian metric on M:

$$g_J(\cdot,\cdot) := \omega(\cdot, J \cdot)$$

• The space $\mathcal{J}(M, \omega)$ of ω -compatible almost complex structures on M is non-empty and contractible.

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Now, let $(\gamma, [\Gamma]) \in \widetilde{\mathcal{P}(\hat{\gamma})}$.

The tangent space to *<i>P*(*γ̂*) at (*γ*, [Γ]) is the space of vector fields *ξ* along *γ* with initial and final vectors in the tangent spaces to L₀ and L₁, respectively, i.e.

$$T_{(\gamma,[\Gamma])}\widetilde{\mathcal{P}(\gamma)} = \{\xi \in \Gamma(\gamma^*(TM)) : \xi(t) \in T_{\gamma(t)M}, \xi(i) \in T_{\gamma(i)}L_i\}$$

- Choose a smooth family $J = \{J_t\}_{0 \le t \le 1} \subset \mathcal{J}(M, \omega)$, which gives rise to a smooth family of Riemannian metrics $\{g_t\}_{0 \le t \le 1}$.
- We define a Riemannian metric on $\widetilde{\mathcal{P}}(\widehat{\gamma})$ as follows: If $\xi, \eta \in T_{(\gamma,[\Gamma])}\widetilde{\mathcal{P}}(\widehat{\gamma})$, put

$$\langle \xi, \eta \rangle := \int_0^1 g_t(\xi(t), \eta(t)) \mathrm{d}t.$$

Gradient

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We are now able to make sense of the gradient flow. Let $(\gamma, [\Gamma]) \in \widetilde{\mathcal{P}(\hat{\gamma})}$ and $\xi \in T_{(\gamma, [\Gamma])} \widetilde{\mathcal{P}(\hat{\gamma})}$. Let $\{\gamma_{\eta}(t)\}_{1-\epsilon_0 \leq \eta \leq 1+\epsilon_0}$ be a smooth homotopy such that $\gamma_1 = \gamma$ and

$$\left. \frac{\partial}{\partial \eta} \right|_{\eta=1} \gamma_{\eta}(t) = \xi(t),$$

and let $\Gamma:[0,1+\epsilon_0]\times[0,1]\to M$ be a smooth homotopy for which

$$\begin{split} & \Gamma(0,t) &= \hat{\gamma}(t) \\ & \Gamma(1,t) &= \gamma(t) \\ & \Gamma(\eta,t) &= \gamma_{\eta}(t), \quad \forall \eta \in [1-\epsilon_0,1+\epsilon_0]. \end{split}$$

For each $\eta,$ we have the homotopy $\Gamma_\eta:[0,1]\times[0,1]\to M$ from $\hat\gamma$ to γ_η defined by

$$\Gamma_{\eta}(s,t) = \Gamma(\eta s,t)$$

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$$d\mathcal{A}_{(\gamma,[\Gamma])}(\xi) = \frac{\partial}{\partial \eta} \Big|_{\eta=1} \mathcal{A}(\gamma_{\eta},[\Gamma_{\eta}]) \\ = -\frac{\partial}{\partial \eta} \Big|_{\eta=1} \int_{\Gamma_{\eta}} \omega \\ = -\frac{\partial}{\partial \eta} \Big|_{\eta=1} \int_{0}^{1} \int_{0}^{1} \omega \left(\frac{\partial \Gamma_{\eta}}{\partial s}, \frac{\partial \Gamma_{\eta}}{\partial t}\right) ds \wedge dt \\ = -\frac{\partial}{\partial \eta} \Big|_{\eta=1} \int_{0}^{1} \int_{0}^{\eta} \omega \left(\frac{\partial \Gamma}{\partial \tilde{s}}, \frac{\partial \Gamma}{\partial t}\right) d\tilde{s} \wedge dt \\ = -\int_{0}^{1} \omega \left(\xi(t), \frac{\partial \gamma}{\partial t}\right) dt \\ = \int_{0}^{1} \omega \left(\frac{\partial \gamma}{\partial t}, \xi(t)\right) dt$$

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With the family of $\omega\text{-compatible}$ almost complex structures $J_t,$ we then have

$$d\mathcal{A}_{(\gamma,[\Gamma])}(\xi) = \int_0^1 \omega \left(J_t \frac{\partial \gamma}{\partial t}, J_t \xi(t) \right) dt$$
$$= \int_0^1 g_t \left(J_t \frac{\partial \gamma}{\partial t}, \xi(t) \right) dt$$
$$= \left\langle J_t \frac{\partial \gamma}{\partial t}, \xi \right\rangle$$

That is, with respect to the Riemannian metric we defined,

$$\operatorname{grad} \mathcal{A}(\gamma, [\Gamma]) = J_t \frac{\partial \gamma}{\partial t}$$

Critical Points

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Applications

grad
$$\mathcal{A}(\gamma, [\Gamma]) = J_t \frac{\partial \gamma}{\partial t}$$

• Since J_t is an automorphism of TM for each t, grad $\mathcal{A}(\gamma, [\Gamma]) = 0$ if and only if $\frac{\partial \gamma}{\partial t} \equiv 0$, i.e. $\gamma \in \mathcal{P}(L_0, L_1)$ is a constant trajectory.

That is:

The critical points of \mathcal{A} are the intersection points $\in L_0 \cap L_1$.

Gradient Flowlines

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Applications

grad
$$\mathcal{A}(\gamma, [\Gamma]) = J_t \frac{\partial \gamma}{\partial t}$$

- If $p, q \in L_0 \cap L_1$, a flowline of $-\operatorname{grad} \mathcal{A}$ from p to q is a smooth function $\tilde{u} : \mathbb{R} \to \widetilde{\mathcal{P}(\hat{\gamma})}$ satisfying
 - $\frac{\mathrm{d}\tilde{u}}{\mathrm{d}s} = -\operatorname{grad}\mathcal{A}, \quad \lim_{s \to -\infty} \tilde{u}(s) = p, \quad \text{and} \quad \lim_{s \to +\infty} \tilde{u}(s) = q.$

Equivalently, we have a strip $u : \mathbb{R} \times [0,1] \to M$ satisfying:

$$\begin{array}{rcl} \displaystyle \frac{\partial u}{\partial s} + J_t \frac{\partial u}{\partial t} & = & 0, \\ \displaystyle \lim_{s \to -\infty} u(s,t) & = & p, \\ \displaystyle \lim_{s \to +\infty} u(s,t) & = & q. \end{array}$$

J-Holomorphic Strips

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Applications

 $\frac{\partial u}{\partial s} + J_t \frac{\partial u}{\partial t} = 0,$ $\lim_{s \to -\infty} u(s,t) \quad = \quad p,$ $\lim_{s \to +\infty} u(s,t) = q.$

- Note that the first equation above is the Cauchy-Riemann equation $\overline{\partial}_J(u) = 0$ for u, with respect to the family $J = \{J_t\}$ of almost complex structures.
- A map u satisfying $\overline{\partial}_J(u) = 0$ is called a *J*-holomorphic strip in (M, ω) . That is, a connecting gradient flowline is a *J*-holomorphic strip.
- Riemann Mapping Theorem $\Rightarrow \mathbb{R} \times [0,1]$ is biholomorphic to $D^2 \{\pm 1\}$, and hence a *J*-holomorphic strip can also be regarded as a closed Whitney disk with two points removed (corresponding to the two critical points p, q)

Finite Energy

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Applications

• If M is not compact, we need to impose an extra condition: The J-holomorphic strips $u : \mathbb{R} \times [0,1] \to M$ must have finite energy, i.e.

$$E(u):=\int_u \omega = \int_0^1 \int_0^1 \left|rac{\partial u}{\partial s}
ight|^2 \mathrm{d}s\mathrm{d}t <\infty.$$

• If M is compact, the limiting conditions

$$\lim_{s \to -\infty} u(s,t) = p, \quad \lim_{s \to +\infty} u(s,t) = q$$

turn out to be equivalent to the finite energy condition.

Moduli Space of *J*-Holomorphic Strips

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Applications

- $\widehat{\mathcal{M}}(p,q;J)$ denotes the space of all smooth *J*-holomorphic strips $u: \mathbb{R} \times [0,1] \to M$ for which $\lim_{s \to -\infty} u(s,t) = p$, $\lim_{s \to +\infty} u(s,t) = q$, $u(s,\cdot) \in \mathcal{P}(L_0,L_1)$, and $E(u) < \infty$.
- $\mathcal{M}(p,q;J)$ denotes the quotient of $\widehat{\mathcal{M}}(p,q;J)$ by the action of \mathbb{R} by reparametrization, i.e. $a \in \mathbb{R}$ acts by

$$u \mapsto u_a(s,t) := u(s-a,t)$$

- If β ∈ π₂(M, L₀ ∪ L₁), M(p,q;β,J) denotes the space of all smooth J-holomorphic strips u ∈ M(p,q;J) with [u] = β.
- $\mathcal{M}(p,q;\beta,J)$ denotes the quotient of $\widehat{\mathcal{M}}(p,q;\beta,J)$ by the usual action of \mathbb{R} by reparametrization.

Maslov Index: One Lagrangian

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Applications

To address the dimension of the moduli space of holomorphic strips, we look at the *Maslov index*. For the moment, consider a single Lagrangian submanifold L of M.

- If $u: (D^2, \partial D^2) \to (M^{2n}, L)$ is smooth, there is a trivial symplectic fibration $u^*(TM) \to D^2$ (since D^2 is contractible).
- Restricting to $\partial D^2 = S^1$, we have a loop of Lagrangian subspaces of $(\mathbb{R}^{2n}, \omega_0)$.
- That is, u induces a loop in the Lagrangian Grassmannian of $\mathbb{R}^{2n},$ i.e. a map

$$u_L: S^1 \to \Lambda(\mathbb{R}^{2n})$$

• The Maslov index of u is the winding number

$$\mu_L(u) := (u_L)_*(1) \in \pi_1(\Lambda(\mathbb{R}^{2n})) \simeq \mathbb{Z}$$

• The Maslov index only depends on the homotopy class, i.e. we have a well-defined homomorphism $\mu_L : \pi_2(M, L) \to \mathbb{Z}$.

Maslov Index: Two Lagrangians

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Applications

Now, back to the two Lagrangian submanifolds L_0 and L_1 of M:

- If $u : \mathbb{R} \times [0,1] \to M$ is a smooth *J*-holomorphic strip in $\widehat{\mathcal{M}}(p,q;J)$, then $u^*(TM)$ is again a trivial symplectic fibration since $\mathbb{R} \times [0,1]$ is contractible.
- Restricting to both L_0 and L_1 , we have two paths $\ell_0 := (u|_{\mathbb{R} \times 0})^*(TL_0)$ and $\ell_1 := (u|_{\mathbb{R} \times 1})^*(TL_1)$ of Lagrangian subspaces, one connecting T_pL_0 to T_qL_0 and the other connecting T_pL_1 to T_qL_1 .
- In general, for two paths $\ell_0, \ell_1 : [0,1] \to \Lambda(\mathbb{R}^{2n})$ of Lagrangian subspaces such that $\ell_0(i)$ and $\ell_1(i)$ are transverse (i = 0, 1), the Maslov index of ℓ_1 relative to ℓ_0 is the (signed) count of instances t at which $\ell_0(t)$ and $\ell_1(t)$ are NOT transverse to each other.
- The index of the holomorphic strip u is the above Maslov index.

Maslov Index: Two Lagrangians

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Example: In \mathbb{C}^n , consider the paths of Lagrangian subspaces

$$\ell_0(t) = \mathbb{R}^n, \ell_1(t) = (e^{i\theta_1(t)\mathbb{R}}) \times \dots \times (e^{i\theta_n(t)\mathbb{R}})$$

where each $\theta_i(t)$ sweeps through 0 and is within π .

The Maslov index of ℓ_1 relative to ℓ_0 is n.

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Example: In \mathbb{R}^2 , consider the strip $u : \mathbb{R} \times [0,1] \to \mathbb{R}^2$ enclosed by $L_0 = x$ -axis, $L_1 = \{(x, x^2 - x) : x \in \mathbb{R}\}.$

The index of the strip u is ind([u]) = 1.

The Moduli Space as a Manifold

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Theorem

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Let L_0, L_1 be compact Lagrangian submanifolds of a closed symplectic manifold (M, ω) . If L_0 and L_1 intersect transversely, then there exists a dense subset $\mathcal{J}_{\mathrm{reg}}(L_0, L_1) \subset C^{\infty}([0, 1], \mathcal{J}(M, \omega))$ such that for $J = \{J_t\}_{0 \leq t \leq 1} \in \mathcal{J}_{\mathrm{reg}}(L_0, L_1)$, p and q in $L_0 \cap L_1$, and $\beta \in \pi_2(M, L_0 \cup L_1)$, the moduli space $\widehat{\mathcal{M}}(p, q; \beta, J)$ is a smooth manifold. Moreover, $\widehat{\mathcal{M}}(p, q; \beta, J)$ has dimension $\mathrm{ind}(\beta)$.

In particular, if $\operatorname{ind}(\beta) = 1$, then $\widehat{\mathcal{M}}(p,q;\beta,J)$ has dimension 1, and hence $\mathcal{M}(p,q;\beta,J)$ has dimension 0.

The Floer Complex

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Applications

 The Floer complex CF(L₀, L₁) is the free Λ-module generated by the intersection points ∈ L₀ ∩ L₁:

$$CF(L_0, L_1) = \bigoplus_{p \in L_0 \cap L_1} \Lambda \cdot p.$$

compact and tranverse Lagrangians L₀, L₁ ⇒ finitely many generators

Transversality

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Applications

What if L_0 and L_1 are not transverse to each other? In particular, what if $L_0 = L_1$?

• Introduce an inhomogeneous Hamiltonian perturbation to the Cauchy-Riemann equation:

$$\frac{\partial u}{\partial s} + J_t(u) \left(\frac{\partial u}{\partial t} - X_t(u) \right) = 0,$$

where X_t is the Hamiltonian vector field associated to a time-dependent Hamiltonian $H_t: M \to \mathbb{R}$.

Strips now converge (as s → ±∞) to trajectories of the flow of X_t starting on L₀ and ending on L₁, and hence the generators of CF(L₀, L₁) are now flowlines γ : [0, 1] → M, γ(t) = X_t(γ(t)) such that γ(i) ∈ L_i.

Novikov Coefficients

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Applications

To define the Floer differential, we would like to work with *Novikov* coefficients:

• The Novikov ring over a field \mathbb{K} is

$$\Lambda_0 = \left\{ \sum_{i=0}^{\infty} a_i T^{\lambda_i} : a_i \in \mathbb{K}, \lambda_i \in \mathbb{R}_{\ge 0}, \lim_{i \to \infty} \lambda_i = +\infty \right\}$$

• The Novikov field Λ is the field of fractions of Λ_0 , i.e.

$$\Lambda = \left\{ \sum_{i=0}^{\infty} a_i T^{\lambda_i} : a_i \in \mathbb{K}, \lambda_i \in \mathbb{R}, \lim_{i \to \infty} \lambda_i = +\infty \right\}$$

• The point: There can be only at most finitely many i for which $\lambda_i < 0$ and $a_i \neq 0$.

The Floer Differential

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• The Floer differential $\partial: CF(L_0, L_1) \to CF(L_0, L_1)$ is the Λ -linear map defined by

$$\partial(p) = \sum_{q \in L_0 \cap L_1, \operatorname{ind}([u])=1} (\#\mathcal{M}(p, q; [u], J)) T^{\omega([u])} q,$$

where $\#\mathcal{M}(p,q;[u],J) \in \mathbb{Z}$ (or $\mathbb{Z}/2$) is the signed (or unsigned) count of points in the moduli space of *J*-holomorphic strips from p to q in the class [u], and $\omega([u]) = \int u^* \omega$ is the symplectic area of u.

- In general, this sum can be infinite. But Gromov's Compactness Theorem \Rightarrow given any energy bound E_0 , there are only finitely many $[u] \in \pi_2(M, L_0 \cup L_1)$ with $\omega([u]) \leq E_0$ for which $\mathcal{M}(p, q; [u], J) \neq \emptyset$.
- Thus, with Novikov coefficients, the sum is well-defined.

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Applications

- In general, we don't always have $\partial^2 = 0$.
 - Floer proved that $\partial^2 = 0$ for $\mathbb{K} = \mathbb{Z}/2$, and under our assumption $\pi_2(M, L_i) = 0$ for i = 0, 1.
 - One can do away with Novikov coefficients in certain cases, such as when one has *exact* Lagrangian submanifolds in an *exact* symplectic manifold.

Compactness

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Applications

Another issue in showing $\partial^2 = 0$: compactness of the moduli space

- Gromov's Compactness Theorem ⇒ any sequence of J-holomorphic curves with uniformly bounded energy admits a subsequence which uniformly converges, up to reparametrization, to a nodal *tree* of J-holomorphic curves.
- unbounded derivatives, thus leading to energy blowing up in the limit, result in bubbling phenomena

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Three possible limiting behaviors:

• strip breaking: when energy concentrates at either end $s\to\pm\infty,$ i.e. p,q

• disk bubbling: when energy concentrates at a point on the boundary of the strip

• sphere bubbling: when energy concentrates at an interior point of the strip

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- Strip breaking corresponds to broken trajectories in ordinary Morse theory.
- As in ordinary Morse theory, if the only limiting behavior is strip breaking, one can show that $\partial^2 = 0$.
- The assumption $[\omega] \cdot \pi_2(M, L_i) = 0$ ensures that disk and sphere bubbles never occur.
- $\bullet\,$ Another way to avoid disk and sphere bubbles: If one can guarantee that such bubbles have index >2
- Still another way: If ambient and Lagrangian submanifolds are exact, energy is constant on a fixed homotopy class [u], and so no disk nor sphere bubbling ocurs.

$$\partial^2 = 0$$

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Sketch of proof that $\partial^2 = 0$, assuming we exclude disk and sphere bubbling: Fix Lagrangians L_0, L_1 , a generic almost complex structure J, and a Hamiltonian perturbation H (to ensure transversality).

- Given $p, q \in L_0 \cap L_1$ and $[u] \in \pi_2(M, L_0 \cup L_1)$ with $\operatorname{ind}([u]) = 2$, we have $\dim \mathcal{M}(p, q; [u], J) = 1$
- Gromov compacness, no disk nor sphere bubbles \Rightarrow the moduli space can be compactified to the space $\overline{\mathcal{M}}(p,q;[u],J)$ of broken strips
- $\overline{\mathcal{M}}(p,q;[u],J) \leftrightarrow \mathcal{M}(p,r;[u'],J) \times \mathcal{M}(r,q;[u''],J)$, where r is any generator of the Floer complex and [u] = [u'] + [u'']
- index additivity \Rightarrow $\operatorname{ind}[u'] + \operatorname{ind}[u''] = 2$
- tranversality \Rightarrow non-constant strips must have $ind \ge 1 \Rightarrow$ strips can only break into two components

$$\partial^2 = 0$$

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• Gluing Theorem \Rightarrow every broken strip is locally the limit of a unique family of index 2 strips, and $\overline{\mathcal{M}}(p,q;[u],J)$ is a 1-manifold with boundary

$$\partial \overline{\mathcal{M}}(p,q;[u],J) = \prod \left(\mathcal{M}(p,r;[u'],J) \times \mathcal{M}(r,q;[u''],J) \right)$$

taken over all $r\in L_0\cap L_1$ and [u]=[u']+[u''] with $\mathrm{ind}([u'])=\mathrm{ind}([u''])=1$

• Choice of orientations and spin structures on L_0 and L_1 equips moduli spaces with natural orientations

$$\partial^2 = 0$$

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Applications

• Oriented number of boundary points of the compact 1-manifold $\overline{\mathcal{M}}(p,q;[u],J)$ is $0 \Rightarrow$

$$\sum \left(\# \mathcal{M}(p,r;[u'],J) \right) \left(\# \mathcal{M}(r,q;[u''],J) \right) T^{\omega([u])} = 0$$

where the sum is taken over all $r\in L_0\cap L_1$ and [u]=[u']+[u''] with $\mathrm{ind}([u'])=\mathrm{ind}([u''])=1$

• Noting that $\omega([u]) = \omega([u']) + \omega([u''])$, summing over all possible [u] gives us that the coefficient of q in $\partial^2(p)$ is 0.

Problem with Disk or Sphere Bubbling

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Why we should worry about disk bubbling:

Consider $M = T^*(S^1) \cong S^1 \times \mathbb{R}$, L_0 a simple closed curve going around M once, and L_1 a homotopically trivial loop intersecting L_0 transversely at two points p, q

•
$$CF(L_0, L_1) = \Lambda p \oplus \Lambda q$$

• If u is the upper strip and v is the lower strip, then

$$\partial(p) = \pm T^{\omega([u])}$$
 and $\partial(q) = \pm T^{\omega([v])}p$.

 $\bullet \, \Rightarrow \partial^2(p) \neq 0$

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• The Lagrangian Floer homology of (L_0, L_1) is the homology of the Floer complex:

$$HF(L_0, L_1) := rac{\ker \partial}{\operatorname{im} \partial}$$

Theorem

Assume that $[\omega] \cdot \pi_2(M, L_i) = 0$ for i = 0, 1. Moreover, when char $\mathbb{K} \neq 2$, assume that L_0, L_1 are oriented and equipped with spin structures. Then, the Floer differential ∂ is well-defined, satisfies $\partial^2 = 0$, and the Floer cohomology

$$HF(L_0, L_1) := H^*(CF(L_0, L_1), \partial)$$

is, up to isomorphism, independent of the chosen almost complex structure J and invariant under Hamiltonian isotopies of L_0 or L_1 .

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- Having shown $\partial^2 = 0$, one still has to show that $HF(L_0, L_1)$ is independent of J and is invariant under Hamiltonian isotopies of L_0 and L_1 .
- Once the invariance has been established, we can now define, for a single Lagrangian submanifold

 $HF(L, L) := HF(L, \psi(L)),$

where ψ is any Hamiltonian diffeomorphism such that L and $\psi(L)$ intersect transversely.

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Proposition

Let L be a compact Lagrangian submanifold of $(M,\omega).$ If $[\omega]\cdot\pi_2(M,L)=0,$ then

 $HF^*(L,L) \simeq H^*(L;\mathbb{Z}/2) \otimes_{\mathbb{Z}/2} \Lambda.$

Thus, if $\psi \in \operatorname{Ham}(M, \omega)$,

- $#(L \cap \psi(L)) \geq \dim_{\Lambda} HF(L, \psi(L))$
 - $= \dim_{\Lambda} HF(L,L)$
 - $= \dim_{\Lambda} \Lambda \otimes_{\mathbb{Z}/2} H^*(L; \mathbb{Z}/2)$

$$= \sum_{j} \operatorname{rank} H^{j}(L; \mathbb{Z}/2)$$

Arnold's Conjecture

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Finally, we have Floer's result, a version of the Arnold conjecture, proved using Lagrangian Floer homology:

Theorem

Let L be a compact Lagrangian submanifold of a closed symplectic manifold (M, ω) and $\psi \in \operatorname{Ham}(M, \omega)$. Assume that $[\omega] \cdot \pi_2(M, L) = 0$. Then

$$\#(L \cap \psi(L)) \ge \sum_{j} \operatorname{rank} H^{j}(L; \mathbb{Z}/2)$$

Arnold's Conjecture

#

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Now let $\psi \in \operatorname{Ham}(M, \omega)$ with non-degenerate fixed points.

- Graph(ψ) is a Lagrangian submanifold of the symplectic manifold $(M \times M, \pi_1^*(\omega) \pi_2^*(\omega))$
- nondegeneracy \Rightarrow Graph(ψ) is transverse to the diagonal $\Delta = \{(x, x) : x \in M\}$
- assuming $\operatorname{Graph}(\psi), \Delta$ satisfy the hypotheses for L_0, L_1 ,

$$\begin{aligned} & (\Delta \cap \operatorname{Graph}(\psi)) &= & \#(\Delta \cap (1 \times \psi)(\Delta)) \\ & \geq & \sum_{j=0}^{2n} \operatorname{rank} H^j(\Delta; \mathbb{Z}/2) \\ & = & \sum_{j=0}^{2n} \operatorname{rank} H^j(M; \mathbb{Z}/2) \end{aligned}$$

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Corollary

Let (M,ω) be a closed symplectic manifold for which $\pi_2(M) = 0$. If $\psi \in Ham(M,\omega)$ has non-degenerate fixed points, then

$$\#(\operatorname{Fix}(\psi)) \ge \sum_{j=0}^{2n} \operatorname{rank} H^j(M; \mathbb{Z}/2).$$

(Not Exactly) An Example

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Example: Consider $M = S^2$ and L an equator in M.

- This DOES NOT satisfy $[\omega] \cdot \pi_1(M, L) = 0$. However, it is a monotone Lagrangian, and Oh showed that Lagrangian Floer homology can still be defined in this case.
- Then, for any Hamiltonian diffeomorphism ψ of M,

$$\#(\psi(L) \cap L) \ge \sum_{i} \operatorname{rank} H^{i}(S^{1}) = 2.$$

• In particular, this shows that L is a non-displaceable Lagrangian in M.

References

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END Thank you for listening!